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(54) CONTROLLING AUTONOMOUS VEHICLES IN CONNECTION WITH TRANSPORT **SERVICES**

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(57)ABSTRACT

Systems for controlling autonomous vehicles are disclosed. Using one or more location detection resources, the system can receive vehicle data from an autonomous vehicle as the autonomous vehicle progresses towards a pickup location of a requesting user and receive requester data from a mobile computing device of the requester. The system can determine when the autonomous vehicle and the requester are at or within a threshold distance of the pickup location. Subsequently, the system can instruct the autonomous vehicle to perform one or more non-driving operations to facilitate use of the autonomous vehicle by the requester.

